Academic Regulations-M.Tech. 2009-10

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR
Academic Regulations For The Award Of Full Time M.Tech. P.G. Degree
(WITH EFFECT FROM THE ACADEMIC YEAR 2009-10)

The Jawaharlal Nehru Technological University Anantapur shall confer M.Tech. Post Graduate degree to candidates who are admitted to the Master of Technology Programs and fulfill all the requirements for the award of the degree.

1.0   ELIGIBILITY FOR ADMISSIONS:

Admission to the above programme shall be made subject to the eligibility, qualifications and specialization prescribed by the University for each programme, from time to time.

Admissions shall be made either on the basis of merit rank obtained by the qualified candidates at an Entrance Test conducted by the University or on the basis of GATE / PGECET score, subject to reservations prescribed by the University or Government policies from time to time.

2.0   COURSE WORK:

2.1   A Candidate after securing admission must pursue the M.Tech. course of study for Four semesters duration.

2.2   Each semester shall be of 20 weeks duration including all examinations.

2.3   A candidate admitted to a programme should complete it within a period equal to twice the prescribed duration of the programme from the date of admission.

3.0   ATTENDANCE:

3.1   A candidate shall be deemed to have eligibility to write end semester examinations if he has put in at least 75% of attendance on cumulative basis of all subjects/courses in the semester.

3.2   Condonation of shortage of attendance up to 10% i.e., from 65% and above and less than 75% may be given by the college on the recommendation of the Principal.

3.3   Condonation of shortage of attendance shall be granted only on genuine and valid reasons on representation by the candidate with supporting evidence.

3.4   If the candidate does not satisfy the attendance requirement he is detained for want of attendance and shall reregister for that semester. He / she shall not be promoted to the next semester.

4.0. EVALUATION:

The performance of the candidate in each semester shall be evaluated subject wise, with a maximum of 100 marks for Theory and 100 marks for practicals, on the basis of Internal Evaluation and End Semester Examination.

4.1   For the theory subjects 60% of the marks will be for the External End Examination. While 40% of the marks will be for Internal Evaluation, based on the better of the marks secured in the two Mid Term-Examinations held, one in the middle of the Semester (I-IV units) and another immediately after the completion of instruction (V-VIII) units with Three questions to be answered out of four in 2hours, evaluated* for 40 marks.
*Note: All the Questions shall be of equal weightage of 10 marks and the marks obtained for 3questions shall be extrapolated to 40 marks, any fraction rounded off to the next higher mark

4.2   For practical subjects, 60 marks shall be for the End Semester Examinations and 40 marks will be for internal evaluation based on the day to day performance.

4.3   For Seminar there will be an internal evaluation of 50 marks. A candidate has to secure a minimum of 50% to be declared successful. The assessment will be made by a board consisting of HOD and two internal experts at the end of IV semester instruction.

4.4   A candidate shall be deemed to have secured the minimum academic requirement in a subject if he secures a minimum of 40% of marks in the End Examination and a minimum aggregate of 50% of the total marks in the End Semester Examination and Internal Evaluation taken together.

4.5   In case the candidate does not secure the minimum academic requirement in any of the subjects (as specified in 4.4.) he has to reappear for the Semester Examination either supplementary or regular in that subject, or repeat the course when next offered or do any other specified subject as may be required.

5.0   RE-REGISTRATION FOR IMPROVEMENT OF INTERNAL EVALUATION MARKS:

Following are the conditions to avail the benefit of improvement of internal evaluation marks.

5.1   The candidate should have completed the course work and obtained examinations results for I & II semesters.

5.2   He should have passed all the subjects for which the Internal evaluation marks secured are more than 50%.

5.3   Out of the subjects the candidate has failed in the examination due to Internal evaluation marks secured being less than 50%, the candidate shall be given one chance for each Theory subject and for a maximum of **three** Theory subjects for Improvement of Internal evaluation marks.

5.4   The candidate has to re-register for the chosen subjects and fulfill the academic requirements.

5.5   For each subject, the candidate has to pay a fee equivalent to one third of the semester tuition fee and the amount is to be remitted in the form of D.D. in favour of the

Registrar, JNTUA payable at Anantapur along with the requisition through the Principal of the respective college.

5.6 In the event of availing the Improvement of Internal evaluation marks, the internal evaluation marks as well as the End Examinations marks secured in the previous attempt(s) for the reregistered subjects stand cancelled.

6.0   EVALUATION OF PROJECT WORK:

Every candidate shall be required to submit thesis or dissertation after taking up a topic approved by the college/ institute.

6.1 Registration of Project work: A candidate is permitted to register for the project work after satisfying the attendance requirement of all the courses (theory and practical courses of I & II Sem)

6.2 An Internal Departmental Committee (I.D.C) consisting of HOD, Supervisor and one internal senior expert shall monitor the progress of the project work.

6.3 The work on the project shall be initiated in the penultimate semester and continued in the final semester. The duration of the project is for two semesters. The candidate can submit Project thesis with the approval of I.D.C. after 36 weeks from the date of registration at the earliest and one calendar year from the date of registration for the project work. Extension of time within the total permissible limit for completing the programme is to be obtained from the Head of the Institution.

6.4 The student must submit status report at least in three different phases during the project work period. These reports must be approved by the I.D.C before submission of the Project Report.

6.5 A candidate shall be allowed to submit the thesis / dissertation only after passing in all the prescribed subjects (both theory and practical) and then take viva voce examination of the project. The viva-voce examination may be conducted once in two months for all the candidates submitted during that period.

6.6 Three copies of the Thesis / Dissertation certified in the prescribed from by the supervisor & HOD shall be presented to the H.OD. One copy is to be forwarded to the University and one copy to be sent to the examiner.

6.7 The college shall submit a panel of three experts for a maximum of 5 students at a time. However, the thesis / dissertation will be adjudicated by one examiner nominated by the University.

6.8 If the report of the examiner is favorable viva-voce examination shall be conducted by a board consisting of the Supervisor, Head of the Department and the examiner who adjudicated the thesis / dissertation. The board shall jointly report candidates work as:

1. Very Good   Grade A
2. Good   Grade B
3. Satisfactory   Grade C
4. Not satisfactory   Grade D

If the report of the viva-voce is not satisfactory (Grade D) the candidate will retake the viva-voce examination after three months. If he fails to get a satisfactory report at the

second viva-voce examination he will not be eligible for the award of the degree unless the candidate is permitted to revise and resubmit the thesis.

7.0 AWARD OF DEGREE AND CLASS:

A candidate shall be eligible for the award of respective degree if he satisfies the minimum academic requirements in every subject and secures 'satisfactory' or higher grade report on his thesis/dissertation and viva-voce. Based on overall percentage of marks obtained, the following class is awarded.

First class with Distinction:	70% or more
First class	below 70% but not less than 60%
Second class	below 60% but not less than 50%

8.0 WITH – HOLDING OF RESULTS:

If the candidate has not paid dues to the university or if any case of in-discipline is pending against him, the result of the candidate shall be withheld and he will not be allowed/ promoted into the next higher semester. The issue of degree is liable to be withheld in such cases.

9.0 TRANSITORY REGULATIONS:

Candidates who have discontinued or have been detained for want of attendance or who have failed after having undergone the course in earlier regulations and wish to continue the course are eligible for admission into the unfinished semester from the date of commencement of class work with the same or equivalent subjects as and when subjects are offered, subject to 4.5 and 2.3 sections. Whereas they continue to be in the academic regulations they were first admitted.

10.0 GENERAL:

   i. The academic regulations should be read as a whole for purpose of any interpretation.

   ii. Disciplinary action for Malpractice / improper conduct in examinations is appended.

   iii. There shall be no places transfer within the constituent colleges and affiliated colleges of Jawaharlal Nehru Technological University Anantapur.

   iv. Where the words "he", "him", "his", occur in the regulations, they include "she", "her", "hers".

   v. In the case of any doubt or ambiguity in the interpretation of the above rules, the decision of the Vice-Chancellor is final.

   vi. The University may change or amend the academic regulations or syllabi at any time and the changes or amendments shall be made applicable to all the students on rolls with effect from the dates notified by the University.

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RULES FOR DISCIPLINARY ACTION FOR MALPRACTICE / IMPROPER CONDUCT IN EXAMINATIONS

	Nature of Malpractices/Improper conduct	Punishment
	If the candidate	
1. (a)	Possesses or keeps accessible in examination hall, any paper, note book, programmable calculators, Cell phones, pager, palm computers or any other form of material concerned with or related to the subject of the examination (theory or practical) in which he is appearing but has not made use of (material shall include any marks on the body of the candidate which can be used as an aid in the subject of the examination)	Expulsion from the examination hall and cancellation of the performance in that subject only.
(b)	Gives assistance or guidance or receives it from any other candidate orally or by any other body language methods or communicates through cell phones with any candidate or persons in or outside the exam hall in respect of any matter.	Expulsion from the examination hall and cancellation of the performance in that subject only of all the candidates involved. In case of an outsider, he will be handed over to the police and a case is registered against him.
2.	Has copied in the examination hall from any paper, book, programmable calculators, palm computers or any other form of material relevant to the subject of the examination (theory or practical) in which the candidate is appearing.	Expulsion from the examination hall and cancellation of the performance in that subject and all other subjects the candidate has already appeared including practical examinations and project work and shall not be permitted to appear for the remaining examinations of the subjects of that Semester/year. The Hall Ticket of the candidate is to be cancelled and sent to the University.
3.	Comes in a drunken condition to the examination hall.	Expulsion from the examination hall and cancellation of the performance in that subject and all other subjects the candidate has already appeared including practical examinations and project work and shall not be permitted for the remaining examinations of the subjects of that semester/year.

4.	Smuggles in the Answer book or additional sheet or takes out or arranges to send out the question paper during the examination or answer book or additional sheet, during or after the examination.	Expulsion from the examination hall and cancellation of performance in that subject and all the other subjects the candidate has already appeared including practical examinations and project work and shall not be permitted for the remaining examinations of the subjects of that semester/year. The candidate is also debarred for two consecutive semesters from class work and all University examinations. The continuation of the course by the candidate is subject to the academic regulations in connection with forfeiture of seat.
5.	Leaves the exam hall taking away answer script or intentionally tears of the script or any part thereof inside or outside the examination hall.	Expulsion from the examination hall and cancellation of performance in that subject and all the other subjects the candidate has already appeared including practical examinations and project work and shall not be permitted for the remaining examinations of the subjects of that semester/year. The candidate is also debarred for two consecutive semesters from class work and all University examinations. The continuation of the course by the candidate is subject to the academic regulations in connection with forfeiture of seat.
6.	Possess any lethal weapon or firearm in the examination hall.	Expulsion from the examination hall and cancellation of the performance in that subject and all other subjects the candidate has already appeared including practical examinations and project work and shall not be permitted for the remaining examinations of the subjects of that semester/year. The candidate is also debarred and forfeits the seat.

7.	Impersonates any other candidate in connection with the examination.	The candidate who has impersonated shall be expelled from examination hall. The candidate is also debarred and forfeits the seat. The performance of the original candidate who has been impersonated, shall be cancelled in all the subjects of the examination (including practicals and project work) already appeared and shall not be allowed to appear for examinations of the remaining subjects of that semester/year. The candidate is also debarred for two consecutive semesters from class work and all University examinations. The continuation of the course by the candidate is subject to the academic regulations in connection with forfeiture of seat. If the impostor is an outsider, he will be handed over to the police and a case is registered against him.
8.	Refuses to obey the orders of the Chief Superintendent/Assistant – Superintendent / any officer on duty or misbehaves or creates disturbance of any kind in and around the examination hall or organizes a walk out or instigates others to walk out, or threatens the officer-in charge or any person on duty in or outside the examination hall of any injury to his person or to any of his relations whether by words, either spoken or written or by signs or by visible representation, assaults the officer-in-charge, or any person on duty in or outside the examination hall or any of his relations, or indulges in any other act of misconduct or mischief which result in damage to or destruction of property in the examination hall or any part of the College campus or engages in any other act which in the opinion of the officer on duty amounts to use of unfair means or misconduct or has the tendency to disrupt the orderly conduct of the examination.	In case of students of the college, they shall be expelled from examination halls and cancellation of their performance in that subject and all other subjects the candidate(s) has (have) already appeared and shall not be permitted to appear for the remaining examinations of the subjects of that semester/year. The candidates also are debarred and forfeit their seats. In case of outsiders, they will be handed over to the police and a police case is registered against them.

9.	If student of the college, who is not a candidate for the particular examination or any person not connected with the college indulges in any malpractice or improper conduct mentioned in clause 6 to 8.	Student of the colleges expulsion from the examination hall and cancellation of the performance in that subject and all other subjects the candidate has already appeared including practical examinations and project work and shall not be permitted for the remaining examinations of the subjects of that semester/year. The candidate is also debarred and forfeits the seat. Person(s) who do not belong to the College will be handed over to police and, a police case will be registered against them.
10.	Uses objectionable, abusive or offensive language in the answer paper or in letters to the examiners or writes to the examiner requesting him to award pass marks.	Cancellation of the performance in that subject.
11.	Copying detected on the basis of internal evidence, such as, during valuation or during special scrutiny.	Cancellation of the performance in that subject and all other subjects the candidate has appeared including practical examinations and project work of that semester/year examinations.
12.	If any malpractice is detected which is not covered in the above clauses 1 to 11 shall be reported to the University for further action to award suitable punishment.	

Malpractices identified by squad or special invigilators

1. Punishments to the candidates as per the above guidelines.
2. Punishment for institutions : (if the squad reports that the college is also involved in encouraging malpractices)
   (i) A show cause notice shall be issued to the college.
   (ii) Impose a suitable fine on the college.
   (iii) Shifting the examination centre from the college to another college for a specific period of not less than one year.

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR

Course Structure and Detailed Syllabi for

M.Tech., Power Electronics and Electrical Drives (PE&ED)
Power Electronics (PE) & Power Electronics & Drives (PED),
Power & Industrial Drives (PID)
Offered by Department of EEE
for affiliated Engineering Colleges 2012-13

I YEAR   I SEMESTER

S. No	Course code	Subject	Theory	Lab.	Credits
1.	9D49101	Modern Control Theory	4		4
2.	9D49102	Microprocessor and Microcontrollers	4		4
3.	9D54103	Principles of Machine modeling Analysis	4		4
4.	9D54104	Analysis of Power Electronic Converters	4		4
5.	9D54105	Power Electronic Control of DC Drives	4		4
6.	9D49106a 9D49106b	**Elective-I** a. Advanced Digital Signal Processing b. Neural Networks and Fuzzy Systems	4		4
7.	9D54107	Power Converters Lab		3	2
		contact periods/week	24	3	26
			Total 27		

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I YEAR   II SEMESTER

S. No	Course Code	Subject	Theory	Lab.	Credits
1.	9D49201	Flexible AC Transmission Systems	4		4
2.	9D49202	HVDC Transmission	4		4
3.	9D54203	Power Electronic Control of AC Drives	4		4
4.	9D54204	Advanced Power Semiconductor Devices & Protection	4		4
5.	9D54205	Modern Power Electronics	4		4
6.	9D49206a 9D49206b	**Elective-II** a. Programmable Logic Controllers b. Energy Auditing, Conservation And Management	4		4
7.	9D54207	Electrical Systems Simulation Lab		3	2
		contact periods/week	24	3	26
			Total 27		

II YEAR   (III & IV Semesters)

S. No	Course code	Subject		credits
1	9D54401	Seminar		2
2	9D54202	Project work		16

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR

M.Tech. I SEMESTER (PEED)   **Th   C**
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(9D49101) MODERN CONTROL THEORY

UNIT –I MATHEMATICAL PRELIMINARIES - Fields, Vectors and Vector Spaces – Linear combinations and Bases – Linear Transformations and Matrices – Scalar Product and Norms – Eigen values, Eigen Vectors and a Canonical form representation of Linear operators – The concept of state – State Equations for Dynamic systems – Time invariance and Linearity – Nonuniqueness of state model – State diagrams for Continuous – Time state models –

UNIT – II   STATE VARIABLE ANALYSIS - Linear Continuous time model for physical systems – Existence and Uniqueness of Solutions to Continuous – Time State Equations – Solutions – Linear Time Invariant Continuous – Time State Equations – State transition matrix and it's properties

UNIT – III   CONTROLLABILITY AND   OBSERVABILITY - General concept of Controllability - General concept of Observability Controllability tests for Continuous – Time Invariant systems - Observability tests for Continuous - Time Invariant systems - Controllability and Observability of state model in Jordan Canonical form - Controllability and Observability Canonical forms of State model

Unit – IV   NON LINEAR SYSTEMS – I - Introduction – Non Linear Systems – Types of Non – Linearities – Saturation – Dead – Zone – Backlash – Jump Phenomenon etc; - Singular Points – Introduction to Linearization of nonlinear systems, properties of Non Linear Systems – Describing function – describing function analysis of nonlinear systems- Stability analysis of Non – Linear systems through describing functions

UNIT – V   NON LINEAR SYSTEMS – II - Introduction to phase – plane analysis, Method of Isoclines for Constructing Trajectories, singular points, phase – plane analysis of nonlinear control systems.

UNIT - VI   STABILITY ANALYSIS - Stability in the sense of Lyapunov, Lyapunov's stability and Lyapunov's instability theorems – Stability Analysis of the Linear Continuous time invariant systems by Lyapunov second method – Generation of Lyapunov functions – Variable gradient method – Krasooviski's method.

UNIT – VII STATE FEEDBACK CONTROLLERS AND OBSERVERS - State Feedback Controller design through Pole Assignment – state observers: Full order and Reduced order

UNIT – VIII OPTIMAL CONTROL - Introduction to optimal control – Formulation of optimal control problems – calculus of variations – fundamental concepts, functional, variation of functional – fundamental theorem of theorem of Calculus of variations – boundary conditions – constrained minimization – formulation using Hamiltonian method – Linear quadratic regulator

REFERENCE BOOKS:
1. Modern Control System Theory by M. Gopal – New Age International – 1984
2. Modern Control Engineering by Ogata. K – Prentice Hall – 1997
3. Optimal control by Kirk

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR

M.Tech. I SEMESTER (PEED)   **Th   C**
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(9D49102) MICROPROCESSORS AND MICROCONTROLLERS

Unit I   Intel 8086/8088   - Architecture, its register organization, Pin diagram, Minimum and Maximum Mode System and Timings, Machine language instruction formats, Addressing modes, Instruction set, Assembler directives.

Unit II   Hardware description - Pin diagram, Minimum and Maximum Mode and Bus Timings, Ready and Wait states and 8086 based micro-computing system

Unit III   ALP Programming & special features - ALP, programming with an assembler, stack structure, Interrupts, Service subroutines and Interrupt programming and Macros.

Unit IV   Advanced Processors - Architectural features of 80386, 486 and Pentium Processors their memory management, Introduction to Pentium Pro Processors their features, RISC Vs CISC Processors.

Unit V   Basic Peripherals & Their Interfacing:- Memory Interfacing (DRAM), PPI- Modes of operation of 8255, interfacing to ADC & DAC

Unit VI Special Purpose of Programmable Peripheral Devices and Their Interfacing: Programmable timer- 8253, PIC 8259A, Display controller, Programmable Communication Interface 8251-USART and their interfacing.

Unit VII   Micro Controllers - Introduction to Intel 8-bit and 16-bit Micro controllers, 8051-Architecture, memory organization, Addressing modes .

Unit VIII Hardware Description of 8051 - Instruction formats, Instruction sets, Interrupt structure and interrupt priorities, Port structures and Operation Linear Counter functions, Different modes of operation and programming Examples.

REFERENCE BOOKS:
1. "The Intel Microprocessors", Architecture, Programming and interfacing by Barry b Brey
2. 8086 Micro Processors by Kenrith J Ayala, Thomson Publishers.
3. Microcontrollers by K.J.Ayala - Thomson Publishers.
4. Micro Processors and Interfacing Programming and Hardware by Douglas V. Hall.
5. The 8088 and 8086 Microprocessor- W.A. Triebel & Avtar Singh- PHI, 4th Edn, 2002.

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M.Tech. I SEMESTER (PEED)   **Th   C**
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(9D54103) PRINCIPLES OF MACHINE MODELING AND ANALYSIS

Unit I: Basic concepts of Modeling

Basic Two-pole Machine representation of Commutator machines, 3-phase synchronous machine with and without damper bars and 3-phase induction machine, Kron's primitive Machine-voltage, current and Torque equations.

Unit II: DC Machine Modeling

Mathematical model of separately excited D.C motor – Steady State analysis-Transient State analysis-Sudden application of Inertia Load-Transfer function of Separately excited D.C Motor-Mathematical model of D.C Series motor, Shunt motor-Linearization Techniques for small perturbations

Unit III   Modeling of Three Phase Induction Machine - I

 Transformation from Three phase to two phase and Vice Versa - Transformation from Rotating axes to stationary axes and vice versa –Park's Transformation and it's physical concept –The Inductance matrix-Mathematical model of Induction machine –Steady State analysis.

UNIT IV Modeling of Three Phase Induction Machine - II

D-Q model of induction machine in Stator reference Frame, Rotor reference Frame and Synchronously rotating reference Frame -Small signal equations of induction machine-d-q flux linkages model derivation- Signal flow graph of the induction machine-Per unit model -Dynamic simulation of induction machine.

Unit V   Modeling of Single Phase Induction Machine

Comparison between single phase and poly-phase induction motor - Cross field theory of single-phase induction machine, steady state analysis – steady state torque

Unit VI Modeling of Synchronous Machine

Synchronous machine inductances –The phase Co-ordinate model-The Space phasor (d-q) model-Steady state operation-Mathematical model of PM Synchronous motor.

Unit VII   Modeling of Special Machines –I

Modelling of Permanent Magnet Brushless DC Motor – Operating principle-Mathematical modeling of PM Brushless DC motor-PMDC Motor Drive Scheme.

Unit VIII   Modeling of Special Machines –II

Mathematical model of Switched Reluctance Motor-Operating principle-Construction and functional Aspects-Average torque and Energy Conversion Ratio-The Commutation windings-SRM modeling-The flux current position curve fitting.

Reference Books:
1. Generalized Theory of Electrical Machines – P.S.Bimbra-Khanna publications-5th edition-1995
2. The Unified Theory of Electrical Machines by C.V.jones, Butterworth- London, 1967
3. Electric Motor Drives Pearson Modeling, Analysis& control -R.Krishnan- Publications-1st edition -2002
4. Electrical Drives- I. Boldea & S.A. Nasar-The Oxford Press Ltd.
5. Electrical Machine Dynamics- D.P. Sengupta & J.B. Lynn- The Macmillan Press
6. Electromechanical Dynamics- Woodson & Melcher   -John Wiley & Sons
7. Analysis of Electrical Machinery – P.C.Krause – McGraw Hill- 1980

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M.Tech. I SEMESTER (PEED)   **Th   C**
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(9D54104) ANALYSIS OF POWER ELECTRONIC CONVERTERS

Unit-I Single Phase AC voltage Controllers
Single Phase AC Voltage Controllers with resistive, resistive-inductive and resistive-inductive-induced emf loads-ac voltage controller's wit PWM control-Effects of source and load inductances –synchronous tap changers –Application- numerical problems

Unit-II Three Phase AC Voltage Controllers
Three Phase AC Voltage controllers-Analysis of Controllers with star and delta connected resistive, resistive –inductive loads-Effects of source and load inductances–Application- numerical problems.

Unit-III Cycloconverters
Single phase to single phase cycloconverters –analysis of midpoint and bridge configurations-three phase to three phase cycloconverters-analysis of Midpoint and bridge configurations-Limitations-Advantages-Applications-numerical problems

Unit –IV Single phase converters
Single phase cycloconverters- Half controlled and fully controlled Converters – Evaluation of input power factor and harmonic factor-Continuous and Discontinuous load current-Single phase dual converters-Power factor improvements-Extinction angle control-symmetrical angle control-PWM single phase sinusoidal PWM-Single phase series converters-–Application- numerical problems

Unit-V Three Phase Converters
Three Phase Converters- Half controlled and fully controlled Converters – Evaluation of input power factor and harmonic factor-Continuous and Discontinuous load current-three phase dual

converters-Power factor improvements-three phase PWM-twelve pulse converters–Application- numerical problems

Unit-VI D.C. to D.C Converters
Analysis of step-down and step up dc to dc converters with resistive and resistive –inductive loads-Switched mode regulators- Analysis of Buck regulators-Boost Regulators-Buck-Boost Regulators-Cuk Regulators- Condition for continuous inductor and capacitor voltage-Comparison of regulators-Multi output boost regulators –advantages –Application- numerical problems

Unit –VII Pulse Width Modulated Inverters (Single Phase Inverter)
Principle of operation- Performance parameters- Single Phase bridge Inverters-Evaluation of output voltage and current with resistive, inductive and capacitive loads-Voltage control of single phase inverters – Single PWM-Multiple PWM-Sinusoidal PWM-modified PWM-phase displacement control-Advanced Modulation techniques for improved performance , Trapezoidal, staircase ,stepped, harmonic injection and delta modulation – Advantage-–Application- numerical problems

Unit VIII Pulse Width Modulated Inverters (Three Phase Inverter)
Three Phase inverters-analysis of 180 degree condition of output voltage and current with resistive, inductive loads-analysis of 120 degree conduction-Voltage control of three phase inverters-sinusoidal PWM-third harmonic PWM-60 degree PWM –space vector modulation- comparison of PWM techniques-Space vector modulation-Comparison of PWM techniques- harmonic reduction –current source inverters-Variable dc link inverter –boost inverters- buck and boost inverter – inverter circuit design – Advantage-–Application- numerical problems

REFERENCES:
1. Power Electronics-Md.H.Rashid –Pearson Education 3rd Edition, 2004
2. Power Electronics- N.Mohan, Tore.M.Undeland, W.P.Robbins –John Wiley,s -2nd Edition.

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M.Tech. I SEMESTER (PEED)　　　　　　　　　　　　　　　**Th　　C**
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(9D54105) POWER ELECTRONIC CONTROL OF DC DRIVES

Unit-1 Controlled Bridge Rectifier (1-Φ) with DC Motor Load - Separately excited DC motors with rectified single phase supply- single phase semi converter and single phase full converter for continuous and discontinuous modes of operation – power and power factor.

Unit-II Controlled Bridge Rectifier (3-Φ) with DC Motor Load - Three phase semi converter and three phase full converter for continuous and discontinuous modes of operation – power and power factor – Addition of Free wheeling diode – Three phase double converter.

Unit-III Three phase naturally commutated bridge circuit as a rectifier or as an inverter - Three phase controlled bridge rectifier with passive load impedance, resistive load and ideal supply – Highly inductive load and ideal supply for load side and supply side quantities, shunt capacitor compensation, three phase controlled bridge rectifier inverter.

Unit-IV Phase Controlled DC Motor Drives - Three phase controlled converter, control circuit, control modeling of three phase converter – Steady state analysis of three phase converter control DC motor drive – Two quadrant, Three phase converter controlled DC motor drive – DC motor and load, converter.

Unit-V Current and Speed controlled DC Motor drives - Current and Speed controllers - current and speed feedback — Design of controllers - Current and Speed controllers – Motor equations – Filter in the speed feedback loop speed controller – current reference generator – current controller and flow chart for simulation – Harmonics and associated problems – sixth harmonics torque.

Unit-VI Chopper controlled DC motor drives - Principle of operation of the chopper – Four quadrant chopper circuit – Chopper for inversion – Chopper with other power devices – model of the chopper –input to the chopper – Steady state analysis of chopper controlled DC motor drives – rating of the devices – Pulsating torque.

Unit- VII Closed loop operation of DC motor Drives - Speed controlled drive system – current control loop – pulse width modulated current controller – hysterisis current controller – modeling of current controller – design of current

Unit-VIII Simulation of DC motor Drives - Dynamic simulations of the speed controlled DC motor drives – Speed feedback speed controller – command current generator – current controller.

REFERENCES
1. Power Electronics and motor control–Shepherd,Hulley, Liang – II Edn, CU Press
2. Electric motor drives modeling, Analysis and control – R. Krishnan – I Edn, PHI.
3. Power Electronic Circuits, Devices and Applications - M.H.Rashid–PHI, I Edn – Fundamentals of Electric Drives – G. K. Dubey – Narosa Publications – 1995.
4. Power Semiconductor drives – S.B. Dewan and A. Straughen – 1975.

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M.Tech. I SEMESTER (PEED)   **Th   C**
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ELECTIVE-I
(9D49106a) ADVANCED DIGITAL SIGNAL PROCESSING
(Common for EPS, EPE, PE & PE&ED)

UNIT-I: Short introduction, Analog to digital and Digital to Analog conversion, sampled and Hold circuit, Continuous time Fourier Transforms.

UNIT-II: Discrete-time signals and systems, Discrete-time Fourier transform- its properties and applications, Fast Fourier Transform (in time-domain and Frequency domain) , IDFT and its properties.

UNIT-III: z- Transform: Definition and properties, Rational z-transforms, Region of convergence of a rational z- Transform, The inverse z- Transform, Z-Transform properties, Computation of the convolution sum of finite-length sequences, The transfer function

UNIT-IV: Digital filter structures: Block Diagram representation, Equivalent structures, Basic FIR Digital Filter structures, Basic IIR Digital Filter structures, Realization of Basic structures using MATLAB, All pass filters, Computational complexity of Digital filter structures.

UNIT V: IIR Digital filter design: Preliminary considerations, Bilinear transformation method of IIR Filter design, Design of low pass IIR Digital filters, Design of High pass, Band pass and band stop IIR digital filters, Spectral Transformations of IIR filter, IIR digital filter design using MATLAB, Computer aided design of IIR digital filters.

UNIT VI: FIR digital filter design: Preliminary considerations, FIR filter design based on windowed Fourier series, Computer aided design of Equiripple Linear phase FIR filters, Design of Minimum phase FIR filters, FIR digital filter design using MATLAB, Design of computationally efficient FIR digital filters.

UNIT VII: Analysis of Finite word length effects: The quantization process and errors, quantization of Fixed point numbers, Quantization of floating point numbers, Analysis of coefficient quantization effects, Analysis of arithmetic round off errors, Low sensitivity digital filters, Reduction of product round off errors using error feedback, Round off errors in FFT algorithms.

UNIT VIII: The basic sample rate alteration devices, Multi rate structures for sampling rate conversion, Multistage design of decimator and interpolator, The Polyphase decomposition, Arbitrary-rate sampling rate converter, Nyquist Filters and some applications of digital signal processing.

TEXT BOOKS
1. Digital Signal Processing- S.K. Mitra, Tata McGraw-Hill, Third Edition, 2006.
2. Principle of Signal Processing and Linear Systems- B.P. Lathi, Oxford International Student Version, 2009
3. Continuous and Discrete Time Signals and Systems- M. Mondal and A Asif, Cambridge, 2007

REFERENCES
1. Digital Signal Processing- Fundamentals and Applications- Li Tan, Indian reprint, Elsevier,2008.
2. Discrete- Time Signal Processing- Alan V. Oppenheim, Ronald W. Schafer, and John R.Buck, Pearson Education, 2008.

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR

M.Tech. I SEMESTER (PEED)   **Th   C**
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ELECTIVE –I
(9D49106b) NEURAL NETWORKS & FUZZY SYSTEMS

Unit-I   Introduction to Neural Networks
Introduction, Humans and Computers, Organization of the Brain, Biological Neuron, Biological and Artificial Neuron Models, Hodgkin-Huxley Neuron Model, Integrate-and-Fire Neuron Model, Spiking Neuron Model, Characteristics of ANN, McCulloch-Pitts Model, Historical Developments, Potential Applications of ANN.

Unit-II Essentials of Artificial Neural Networks
Artificial Neuron Model, Operations of Artificial Neuron, Types of Neuron Activation Function, ANN Architectures, Classification Taxonomy of ANN-Connectivity, Neural Dynamics (Activation and Synaptic), Learning Strategy (Supervised, Unsupervised, Reinforcement), Learning Rules, Types of Application.

Unit-III   Feed Forward Neural Networks
Introduction, Perceptron Models: Discrete, Continuous and Multi-Category, Training Algorithms: Discrete and Continuous Perceptron Networks, Perceptron Convergence theorem, Limitations of the Perceptron Model, Applications.

Multilayer Feed Forward Neural Networks -Credit Assignment Problem, Generalized Delta Rule, Derivation of Backporpagation (BP) Training, Summary of Backpropagation Algorithm, Kolmogorov Theorem, Learning Difficulties and Improvements.

Unit-IV Associative Memories - Paradigms of Associative Memory, Pattern Mathematics, Hebbian Learning, General Concepts of Associative Memory (Associative Matrix, Association Rules, Hamming Distance, The Linear Associator, Matrix Memories, Content Addressable Memory), Bidirectional Associative Memory (BAM) Architecture, BAM Training Algorithms: Storage and Recall Algorithm, BAM Energy Function, Proof of BAM Stability Theorem.
Architecture of Hopfield Network: Discrete and Continuous versions, Storage and Recall Algorithm, Stability Analysis, Capacity of the Hopfield Network.

Unit-V Self-Organizing Maps (SOM) and Adaptive Resonance Theory (ART) - Introduction, Competitive Learning, Vector Quantization, Self-Organized Learning Networks, Kohonen Networks, Training Algorithms, Linear Vector Quantization, Stability- Plasticity Dilemma, Feed forward competition, Feedback Competition, Instar, Outstar, ART1, ART2, Applications.

Unit-VI   Classical & Fuzzy Sets -Introduction to classical sets – properities, Operations and relations; Fuzzy sets, Membership, Uncertainity, Operations, Properities, fuzzy relations, cardinalities, membedship functions.

Unit-VII   Fuzzy Logic System Components - Fuzzification, Membership Value assignment, development of rule base and decision making system, Defuzzification to crisp sets, Defuzzification methods.

Unit-VIII   Applications - Neural network applications: Process identification, Fraction Approximation, Control and Process Monitoring, Fault diagnosis and Load forecasting.
Fuzzy logic applications: Fuzzy logic control and Fuzzy classification.

TEXT BOOK:
1. Neural Networks, Fuzzy logic , Gnenetic algorithms: synthesis and applications by Rajasekharan and Rai- PHI Publication.
2. Introduction to Artificial Neural Systems- Jacek M.Zurada, Jaico Publishing House, 1997.

REFERENCE BOOKS:
1. Neural and Fuzzy Systems: Foundation, Architectures and Applications, - N. Yadaiah and S. Bapi Raju, Pearson Education
2. Neural Netwroks – James A Freeman and Davis Skapura, Pearson, 2002
3. Neural Netwroks – Simon Hykins, Pearson Education.
4. Neural Engineering by C. Eliasmith and CH. Anderson, PHI.
5. Neural Netwroks and Fuzzy Logic System by Brok Kosko, PHI   Publications

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR

M.Tech. II SEMESTER (PEED)   Th   C
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(9D49201) FLEXIBLE A.C. TRANSMISSION SYSTEMS

Unit 1:
FACTS concepts: Transmission interconnections power flow in an AC system, loading capability limits, Dynamic stability considerations, importance of controllable parameters basic types of FACTS controllers, benefits from FACTS controllers.

Unit 2:
Voltage source converters: Single phase three phase full wave bridge Converters transformer connections for 12 pulse 24 and 48 pulse operation.

Unit 3:
 Three level voltage source converter, pulse width modulation converter, basic concept of current source Converters, and comparison of current source converters with voltage source converters.

Unit 4:
Static shunt compensation: Objectives of shunt compensation, mid point voltage regulation voltage instability prevention, improvement of transient stability, Power oscillation damping.

Unit 5:
Methods of controllable var generation, variable impedance type static var generators switching converter type var generators hybrid var generators.

Unit 6:
SVC and STATCOM: The regulation and slope transfer function and dynamic performance, transient stability enhancement and power oscillation damping operating point control and summary of compensator control.

Unit 7:
Static series compensators: concept of series capacitive compensation, improvement of transient stability, power oscillation damping.

Unit 8:
Functional requirements, GTO thyristor controlled series capacitors (GSC), thyristor switched series capacitor (TSSC).and thyristor controlled series capacitor (TCSC) control schemes for GSC TSSC and TCSC.

Text Book:
"Understanding FACTS Devices" N. G. Hingorani and L. Guygi. IEEE Press Publications 2000.

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M.Tech. II SEMESTER (PEED) **Th** **C**

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(9D49202) H.V.D.C. TRANSMISSION

Unit-1 :
H.V.DC Transmission : General consideration , Power Handling Capabilities of HVDC lines , Basic Conversion principles , static converter configuration.

Unit-2:
Static Power Converters: 3 pulse, 6 pulse & 12 pulse converters, converter station and terminal equipment communication process, Rectifier and inverter operation, equivalent circuit for converter- special futures of converter transformers.

Unit-3:
Harmonics in HVDC systems, harmonicas elimination, AC & DC filter

Unit-4:
Control of HVDC converter and systems: constant current, constant extinction angle and constant ignition angle control. Individual phase control and equidistant firing angle control, DC power flow control

Unit-5:
Interaction between HVAC & DC systems –voltage interaction, harmonic instability problems and DC power modulation.

Unit-6:
Multi-terminal DC link and systems; series, parallel and series parallel systems, their operation and control.

Unit-7:
Transient over voltage in HVDC systems: Over voltages due to disturbance on DC side, over voltages due to DC and AC side line faults.

Unit-8:
Converter faults and protection in HVDC systems: Converter faults, over current protection- valve group and DC line protection. Over voltage protection of converters, surge arresters.

REFERENCES:
1.E.W.Kimbark: Direct current Transmission, Wiely inter Science- New york.
2.J.Arillaga: H.V.D.C.Tranmission peter peregrilnus ltd., London UK 1983
3.K.R.Padiyar: High Voltage Direct current Transmission, Wiely Eastern Ltd
4.E.Uhlman: Power Transmission by Direct Current Springer Verlag, Berrlin

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M.Tech. II SEMESTER (PEED)

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(9D54203) POWER ELECTRONIC CONTROL OF AC DRIVES

Unit-I Introduction to AC drives
Introduction to motor drives-torque production- Equivalent circuit analysis-Speed-Torque characteristics with variable voltage operation, variable frequency operation, constant v/f operation-Induction motor characteristics in constant torque and field weakening regions

Unit-II Control of Induction motor drives at stator side
Scalar control-Voltage fed inverter control-Open loop volts/Hz Control-Speed control slip regulation- Speed control with torque and flux control-Current controlled voltage fed inverter drive-Current fed inverter control-Independent current and frequency control-Speed and flux control in current fed inverter drive-Volts/Hertz Control current fed-Inverter drive-Efficiency optimization control by flux program

Unit-III Control of Induction motor at rotor Side
Slip power recovery drives-Static Kramer Drive-Phasor diagram-Torque expression-Speed control of Kramer Drive-Static Scheribus Drive- Modes of operation

Unit-IV Vector control of Induction motor Drives
Principles of Vector Control-Vector Control Methods-Direct method of Vector control-Adaptive control principles-Self tuning regulator-Model referencing control

Unit-V Control of Synchronous motor Drives
Synchronous motor and its characteristics – control strategies – constant torque angle control-Unity power factor control-Constant mutual flux linkage control

Unit-VI Controllers
Flux weakening operation- Maximum speed-Direct flux weakening algorithm – Constant torque mode controller- Flux Weakening controller- Indirect flux weakening – Maximum permissible torque-Speed control scheme- Implementation strategy – Speed controller design

Unit-VII Variable Reluctance motor Drive
Variable reluctance motor drives- Torque Production in the variable reluctance motor- Drive characteristics and control principles- Current control variable reluctance servo drive.

Unit VIII Brushless DC motor Drives
Three phase full wave Brushless dc motor – Sinusoidal type of Brushless dc motor-Current controlled Brushless dc servo drives

REFERENCES
1. Electric Motor Drives modeling, analysis and control R.Krishnan, Pearson Publication,1/e -2002
2. Modern Power Electronics and AC drives-B.K Bose-Pearson Publication -1ST Edition
3. Power Electronic Control of AC motors- MD Murphy & FG Turn Bull Pergman Press(For Chapters II,III, V) – 1st Edition
4. Power Electronics and AC drives-B.K Bose-Prentice Hall Publication -1ST Edition
5. Power Electronics Circuits , Devices and Application- M.H Rashid –PHI 1995
6. Fundamentals of Electric Drives –GK Dubey- Narora Publications -1995
7. Power Electronics and Variable Frequency drives-B.K.Bose-IEEE press-Standard publication-1ST Edition-2002

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M.Tech. II SEMESTER (PEED) **Th C**
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(9D54204) ADVANCED POWER SEMICONDUCTOR DEVICES AND PROTECTION

Unit I BJTs
Introduction- vertical power transistor structures-I-V characteristics-physics of BJT operation switching characteristics-break down voltages-second break down-on-state losses-safe operation areas design of drive circuits for BJTs-snubber circuits for BJTs and darlingtons

Unit-II Power MOSFETs
Introduction-basic structures-I-V characteristics-physics of device operation-switching characteristics-operation limitations and safe operating areas-design of gate drive circuits-snubber circuits

Unit III Gate Turn-Off Thyristors
Introduction-basic structures-I-V characteristics-physics of device operation-GTO switching characteristics-snubber circuits-over protection of GTOs.

Unit IV Insulated Gate Bipolar Transistors
Introduction-basic structures-I-V characteristics-physics of device operation-Latch in IGBTs-switching characteristics-Device limits and safe operating areas-drive and snubber circuits.

Unit V Emerging Devices and Circuits
Introduction-Power junction field effect transistors-field controlled Thyristor-JFET based devices versus other power devices-MOS controlled Thyristors-high voltage integrated circuits-new semiconductor materials

Unit VI Passive Components and Electromagnetic compatibility
Introduction-design of inductor-transformer design-selection of capacitors-resistors current measurements-heat sinking circuit lay out –Electromagnetic Interference (EMI)-Sources of EMI-Electromagnetic Interference in Power Electronic Equipment

Unit VII Noise
Noise sources in SMPS-Diode Storage Charge Noise-Noise generated due to switching-Common noises sources in SMPS-Noises Due to High frequency transformer-How the conducted noise is measured - minimizing EMI-EMI shielding-EMI standards.

UNIT-VIII Protection of Devices & Circuits
Cooling & Heat sinks – Thermal modeling of powerswitching devices- snubber circuits – Reverse recovery transients – Supply and load side transients – voltage protections – current protections.

Reference books
1. Power Electronics Circuits, Devices and Applications – M.H.Rashid-PHI-
2. Power Electronics –Converters, Applications and Design – Mohan and Undeland-John Wiley&Sons
3. Power Electronics Circuits-Vithayathil
4. Power Electronics Circuits-W.C. Lander

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M.Tech. II SEMESTER (PEED)   **Th   C**

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(9D54205) MODERN POWER ELECTRONICS

UNIT I: Modern power semiconductor devices
Modern power semiconductor devices- MOS Turn Off Thyristor (MTO) – Emitter Turn Off Thyristor (ETO) – Integrated Gate – Commutated thyristor (IGCTs) – MOS – controlled thyristors (MCTs) – Static induction Thyristors (SITHs) – Power integrated circuits (PICs) – Symbol, structure and equivalent circuit- comparison of their features.

UNIT-II: Resonant pulse inverters:
Resonant pulse inverters – series resonant inverters- series resonant inverters with unidirectional switches – series resonant inverters with bidirectional switches- analysis of half bride resonant inverter- evaluation of currents and Voltages of a simple resonant inverter – analysis of half bridge and full bridge resonant inverter with bidirectional switches – Frequency response of series resonant inverter- for series loaded inverter – for parallel resonant inverters – Voltage control of resonant inverters-class E resonant inverter – class E resonant rectifier- evaluation of values of C's and L's for class E inverter and Class E rectifier – numerical problems.

UNIT-III: Resonant Converters:

Resonant converters- zero current switching resonant converters – L type ZCS resonant converter-M type ZCS resonant converter – zero voltage Switching resonant converters – comparison between ZCS and ZVS resonant converters- Two quadrant ZVS resonant converters – resonant dc – link inverters- evaluation of L and C for zero current switching inverter – Numerical problems.

UNIT-IV Multilevel Inverters:

  Multilevel concept- Classification of multilevel inverters – Diode clamped Multilevel inverter-Principle of operation – main features- improved diode clamped inverter – principle of operation – Flying capacitors multilevel inverter – principle of operation – main features.

UNIT-V: Multilevel inverters (continued)

Cascaded multilevel inverter – principle of operation – main features- multilevel inverter applications – reactive power compensation – back to back intertie system – adjustable drives – switching device currents – dc link capacitor voltage balancing –features of Multilevel inverters – comparisons of multilevel converters.

UNIT -VI: DC Power supplies:

DC power supplies – classification- switched mode dc power supplies – fly back Converter-forward converter- push –pull converter –half bridge converter –Full bridge converter – Resonant DC power supplies- bidirectional power supplies- Application.

UNIT -VII: AC Power Supples:

AC power supplies – classification – switched mode ac power supplies Resonant AC power supplies-bidirectional ac power supplies – multistage conversions- control circuits- applications.

UNIT-VIII: Power conditioners and Uninterruptible Power Supplies:

Introduction- power line disturbances – power conditioners- uninterruptible power supplies-applications.

TEXT BOOKS:

1. Power Electronics: Mohammed H.Rashid-Pearson Education- Third Edition –first Indian reprint-2004
2. Power Electronics – Ned Mohan, Tore M.Undeland and William P.Robbind – John wiley & Sons – Second Edition.

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M.Tech. II SEMESTER (PEED)　　　　　　　　　　　　　　**Th　C**
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ELECTIVE II
(9D49206a) PROGRAMMABLE LOGIC CONTROLLERS

Unit 1:
PLC basics: PLC system, I/O modules and interfacing, CPU processor, programming equipment, programming formats, construction of PLC ladder diagrams, devices connected to I/O modules.

Unit 2:
PLC programming: Input instructions, Outputs, operational procedures, programming examples using contacts and coils, drill press operation .

Unit 3:
Digital logic gates, programming in the Boolean algebra system, conversion examples. Ladder diagrams for process control: Ladder diagrams and sequence listings, ladder diagram constructions and flow charts for spray process system.

Unit 4:
PLC registers : characteristics of registers module addressing, holding registers,Input registers, Output registers.

Unit 5:
PLC functions: Timer functions and industrial applications, counters, counter function industrial applications, arithmetic functions, number comparison

Unit 6:
Data handling functions: SKIP, master control relay, jump, move, FIFO, FAL, ONS , CLR and SWEEP functions and their applications.

Unit 7:
Bit pattern and changing a bit shift register, sequence functions and applications, controlling of two axis and three axis robots with PLC, matrix functions.

Unit 8:
Analog PLC operation : Analog modules and systems, analog signal processing, multi bit data processing, analog output application examples, PID principles, position indicator with PID control, PID modules, PID tuning, PID functions.

REFERENCES:
1. Programmable logic controllers-Principle and applications by John W.Webb and Ronald A.Reiss, fifth edition ,PHI.
2. Programmable logic controllers- Programming Method and applications by JR Hackworth and F.D Hackworth Jr.- Pearson, 2004.

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M.Tech. II SEMESTER (PEED)   **Th   C**
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ELECTIVE-II
(9D54207) ENERGY AUDITING, CONSERVATION & MANAGEMENT
(Common to EPS,EPE,PE,PE&ED)

Unit I Basic principles of Energy audit:
Energy audit- definitions, concept , types of audit, energy index, cost index ,pie charts, Sankey diagrams , load profiles, Energy conservation schemes- Energy audit of industries- energy saving potential ,energy audit of process industry, thermal power station, building energy audit

Unit II Energy management-I
Principles of energy management, organizing energy management program, initiating, planning , controlling, promoting, monitoring, reporting.

Unit III Energy management-II
Energy manger, Qualities and functions , language ,Questionnaire - check list for top management

Unit IV Energy efficient Motors
Energy efficient motors , factors affecting efficiency, loss distribution , constructional details , characteristics - variable speed , variable duty cycle systems, RMS hp- voltage variation-voltage unbalance- over motoring- motor energy audit

Unit V Power Factor Improvement, Lighting
Power factor – methods of improvement , location of capacitors , Pf with non linear loads, effect of harmonics on p.f. , p.f motor controllers - Good lighting system design and practice , lighting control ,lighting energy audit

Unit VI Energy Instruments
Energy Instruments watt meter, data loggers, thermocouples, pyrometers, lux meters, tongue testers, application of PLC's

Unit VII Economic aspects and analysis
Economics Analysis-Depreciation Methods , time value of money , rate of return , present worth method , replacement analysis , life cycle costing analysis - Energy efficient motors

Unit-VIII Computation of Economic Aspects
Calculation of simple payback method , net present worth method - Power factor correction, lighting - Applications of life cycle costing analysis, return on investment .

REFERENCE BOOKS:
1) Energy management by W.R. Murphy & G. Mckay Butter worth, Heinemann publications.
2) Energy management by Paul o' Callaghan, Mc-graw Hill Book company-1/e,1998
3) Energy efficient electric motors by John C. Andreas, Marcel Dekker Inc Ltd-2/e, 1995
4) Energy management hand book by W.C.Turner, john Wiley and sons
5). Energy management and good lighting practice: fuel efficiency- booklet12-EEO

AWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR
M.Tech. IV SEMESTER (PEED)   **C**
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(9D54401) SEMINAR

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR
M.Tech. IV SEMESTER (PEED)   **C**
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(9D54402) PROJECT WORK

The Project Work should be on a contemporary topic relevant to the core subjects of the course. It should be original work of the candidate.

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